

Geo++'s Experiments on Android GNSS Raw Data

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Outline



- SSRPOST concept
- Android Applications
- Absolute Positioning
- Ruler App
- Conclusions and Future Work



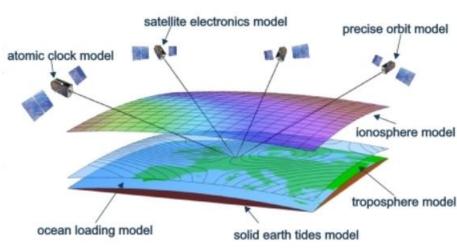
SSRPOST concept



State Space Representation (SSR)



 all physical errors acting on GNSS observations are separated, modelled and represented by an appropriate and flexible manner describing the GNSS state (SSR)



- effective corrections of GNSS errors from SSR
- possibility to support various scalable applications
- time and spatial information on the GNSS state stored in SSR files
- any correction data can be retrieved from SSR in real-time and post-processing

SSR based Post-Processing



- Geo++® GNSMART performs State Space Monitoring providing SSR in real-time
- user uploads RINEX data to a service
- rover positioning algorithm using SSR based
 Network RTK run by the server
- user downloads coordinates and trajectories



Android Applications



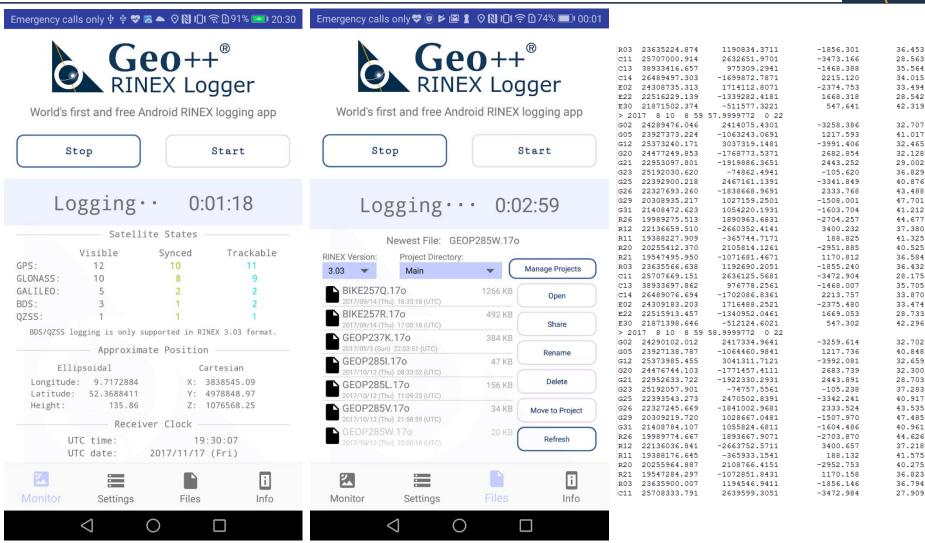
Android Applications (1/2)



- with Android 7.0 (Nougat) possibility to process GNSS raw data
- Geo++®RINEX Logger app which can write observation data into RINEX files to allow post processing and precise positioning
- chance to investigate precise positioning with smartphones and tablet computers
- focus on possible application in real-time

Android Applications (2/2)







Absolute Positioning



Absolute Positioning (1/3)



Idea:

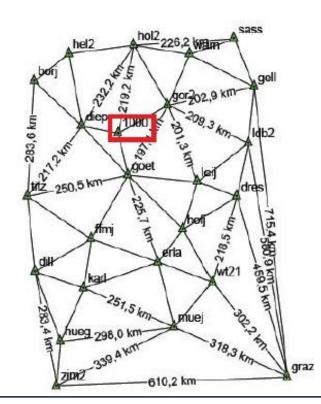
- logging of RINEX 2.11 files
- use of SSR Post concept

Problem settings:

- device used: tablet computer Nexus 9
- network: extended German BKG GREF network
- average stations distance: 211 km
- technique: SSR based Network RTK

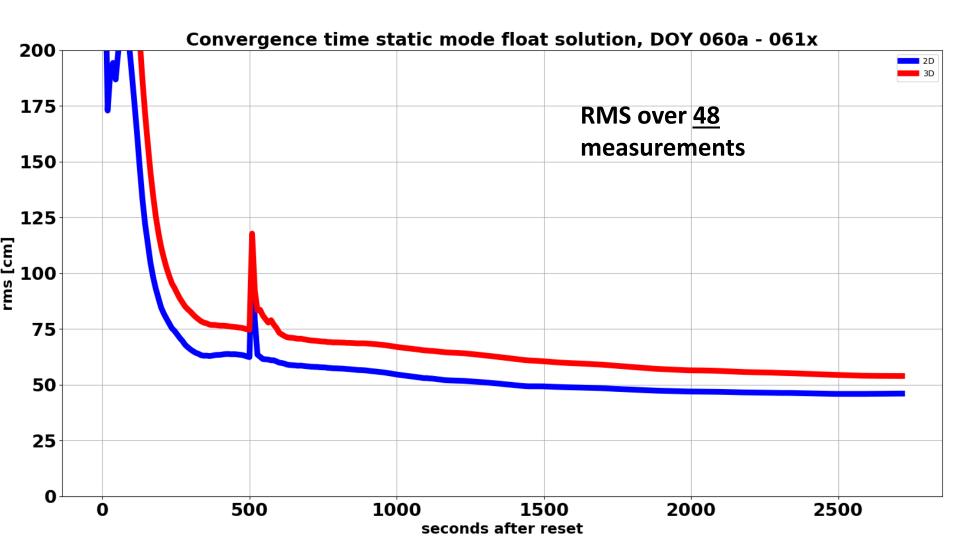
Objective:

get the <u>absolute position</u>
 <u>of a Android device</u> on the
 roof of the Geo++ building



Absolute Positioning (2/3)





Absolute Positioning (3/3)



Comments:

- no ambiguity fixing possible → float solution
- after 5 min roughly 60 cm 2D positioning precision
- no real time application for absolute positioning
- good result considering a network of 210 km average distance
- static mode test
- can we track a path in kinematic mode?

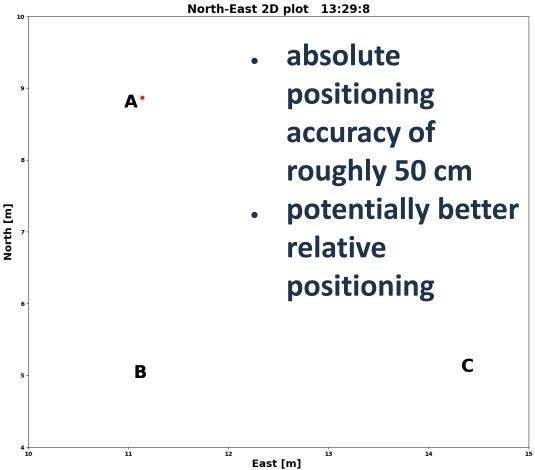
Path tracking



objective: follow a trajectory

• location: roof of the Geo++ building, 3 pillars of known coordinates are

considered





Ruler App



Ruler App(1/3)



Idea:

- logging of Rinex 2.11 files
- use of SSRPOST concept
- download a trajectory

Objective:

 measure the <u>distance</u> <u>between two points</u>

Problem settings:

- devices used: tablet computer Nexus 9,
 smartphone Samsung Galaxy S9
- network: extended BKG German GREF network
- average stations distance: 211 km
- technique: SSR based Network RTK

Ruler App(2/3)

Device:

Smartphone Samsung galaxy 9 (Android 8)

Results w.r.t. a known length (9.87 m and 2.39 m) over 37 measurements:

- RMS = 7.74 cm
- . STD = 4.47 cm



Ruler App(3/3)







- volume down button: start/stop
- indicators of:
 - satellites
 - distance value and accuracy
 - processing status (up to 30 s)
 - GNSS measurements (acoustic indicator)



Conclusions and Future Work



Conclusions



- no chance to fix ambiguities due to different phase biases
- 5 min convergence time to get 60 cm precision absolute positioning in static mode using SSR data from a sparse network → too slow for real time applications
- Ruler App to measure distances in near real time
- error roughly 8 cm RMS w.r.t. known distance
- performance depends on the satellites availability → it will improve with Galileo
- performance dependency on the device and Android version (7 or 8)

part of the present work is protected by patents

Future Work



solve the phase bias issue to fix ambiguities and

do high accuracy positioning

setting up the Ruler App in real time

find future applications

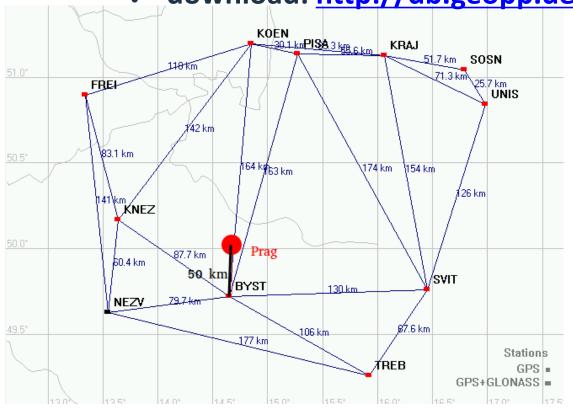


Test the App



available DEMO: test the Ruler App in Prague

download: http://db.geopp.de/ruler.html



acknowledgements to CNH Industrial to provide reference stations data access

Thank you for your attention