Absolute Receiver Antenna Calibrations with a Robot



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Motivation and Goal



- problems with existing field calibration procedure
- problems with absolute chamber calibration results
- PCV urgently needed for mixed antenna type applications (e.g. RTK networks, engineering tasks)
- separation of multipath (MP) and phase variations (PCV)
- absolute PCV independent from reference antenna
- high resolution and precision for PCV
- site and location independent
- field procedure

Development of Absolute PCV Field Calibration



- siderial day differences (1992), first PCV calibrations (1992–1993)
- close cooperation with IfE (since 1995)
- spherical harmonics PCV model, post-processing with GEONAP (1995)
- development of antenna mounts (1996–2000)
- absolute calibrations and detailed analysis (1995–1999)
- automated absolute PCV field calibration in real-time using robot (2000)
- operational absolute PCV field calibration (since 2000)
 - publication of absolute PCV for AOAD/M_T (2000)
 - proposal of GPP_NULLANTENNA (2000)
 - absolute PCV supplied for analysis/verification/use (2000–2001)
 - Geo++ GNPCVDB antenna database (2001)

Development of Multipath Elimination Techniques and PCV Separation



- siderial differences in post-processing
 - first approach
 - observation on two days
 - same geometry/environment

eliminates MP

- short-term differences in real-time
 - operational procedure
 - same MP for subsequent epochs eliminates MP
- PCV reintroduced by orientation changes (rotations and tilts)

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Development of Automated Antenna Mount

- orientation changes of antenna required
- mount for rotating and tilting antenna
 - precise, fixed and stable rotation point
 - automation
 - operational procedure
- finally use of a robot
 - fast changes
 - automated robot

guidance

- real-time



1998

1996





Development of Robot Calibration Procedure



- corrections for robot required
- accuracy for antenna positions : 0.2 0.3 mm



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Details on Absolute PCV Field Calibration

- homogeneous coverage of antenna
 - 6000 8000 different positions
- dynamic robot guidance
 - depends on satellite constellation
 - optimizes observation time
- dynamic elevations mask
 - satellites with high elevation (>18°)
 - actual negative elevation (-5°) used



Absolute

Relative





Analysis of Operational Absolute PCV Field Calibrations









- different locations (Geo++, IfE)
- different times (days, seasons, ...)
- different weather (temperature, rain, snow, wind, ...)
- different robots (hardware, robot calibrations, performance, ...)
- different reference antennas (all major manufacturers)
- different GPS receivers (all major manufacturers)
- different north orientations
- different mounting on robot



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Repeatability and Accuracy of Absolute PCV Field Calibration

0.010

0.005

0.000

-0,005

-0.010

-0.015

100

Lo PCV [m]



0.010

0.005

0.000

-0,005

-0.010

-0.015

example LEIAT303

- absolute L0 PCV : -10 to 15 mm range
- std. dev. of L2 PCV : 0.2 to 0.4 mm range
- difference L0 PCV 5 month apart : 1 mm mean, except horizon



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Characteristics of Absolute PCV Field Calibration



- absolute 3D offset
- absolute PCV
- PCV from (<) 0° to 90° elevation
- 0° to 360° azimuthal PCV
- simultaneous L1, L2 GPS and GLONASS PCV
- high resolution and precision
- free of multipath influence
- site and location independent

- at least two independent calibrations
- duration of several hours
- standard deviation 0.2–0.3 mm (1 sigma) for complete PCV (offset plus PCV)
- verification of accuracy through repeatability

Verification of Absolute PCV



- concern "15 ppb scale" for global networks
- experiment simulating "large network"
 - inclined and rotated AOAD/M_T simulates
 geographical separation
 - no effects from atmosphere, orbits, satellite
 antenna using short baseline, true reference
- coordinates from 24 h data, L0 + tropospheric scale parameter
- proof by comparing absolute and relative PCV performance





Effect of Radome Construction



 difference absolute L0 PCV LEIAT504 / LEIAT504 LEIS
 : -4 to 2 mm range



 difference absolute L0 PCV LEIAT504 / LEIAT504 SCIS
 : –14 mm range





Effect of Radome Construction



- difference absolute L0 PCV ASH700936M_E/ASH700936M_E SNOW
 : -2 to 4 mm range
- difference absolute L0 PCV TRM29659.00/TRM29659.00 TCWD
 : -8 to 8 mm range



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Individual or Type Mean PCV Correction



- individual calibration best choice
 - most antennas not accessible
 - option for new installations
- type mean suitable for other applications
 - simple procedure
 - uncertainty remains

- significant differences between antenna types observed
 - manufacturing series
 - assembling errors
 - outliers even for "Dorne
 Margolin Type" choke ring
 antenna

Example of Individual PCV Difference



- "Dorne Margolin Type" choke ring antenna
- best geodetic antenna type
- example of outlier
 - primarily L1 east offset
 - effect for L0 absolute PCV
 - : -6 to 8 mm range
- different manufacturers
 - 1 outlier out of 10 antennas
 - 1 outlier out of 26 antennas

Typ –Individual Offset	dNorth [mm]	dEast [mm]	dHeight [mm]
L1	-0.2	-4.9	-1.0
L2	+0.1	+0.7	-0.1



Benefits of Absolute PCV Field Calibration and Correction



- high precision absolute PCV
- reliable azimuthal PCV
- separation of error components possible (e.g. station MP calibration, atmospheric parameter)
- unbiased absolute positioning
- mixed antenna type application possible (e.g. RTK networks)
- engineering application with inclined antennas (negative elevation)
- ...

Geo++ GNPCVDB Antenna Database



- type means from calibrated antennas
- rigorous adjustment using complete variance–covariance matrix of individual calibrations
- about 64 different antenna types (Dec. 2001)
 - 344 individual calibrated antennas
 - 1939 individual calibrations
- public information on e.g. PCV pattern shape, etc.
- license for access and use of absolute PCV
- http://gnpcvdb.geopp.de/

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bmb+f



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